	Power Electronics (EE 5 th Semester)
	Unit 3: CHOPPERS
1	Choppers converter
	a) AC to DC
	b) DC to AC
	c) DC to DC
	d) AC to AC
2	A chopper may be thought as a
	a) Inverter with DC input
	b) DC equivalent of an AC transformer
	c) Diode rectifier
	d) DC equivalent of an induction motor
3	Which device can be used in a chopper circuit?
	a) BJT
	b) MOSFET
	c) GTO
	d) All of the mentioned
4	A chopper is a
	a) Time ratio controller
	b) AC to DC converter
	c) DC transformer
	d) High speed semiconductor switch
5	What is the duty cycle of a chopper?
	a) Ton/Toff
	b) Ton/T
	c) T/Ton
	d) Toff x Ton
6	The load voltage of a chopper can be controlled by varying the
	a) duty cycle
	b) firing angle
	c) reactor position
7	d) extinction angle
/	The values of duty cycle (α) lies between
	a) $0 < \alpha < 1$
	b) $0 \ge \alpha \ge 1$
	c) $0 < 0 < 100$
8	If T is the time period for a chopper circuit and α is its duty cycle, then the
0	chopping frequency is
	a) Ton/α
	b) $Toff/\alpha$
	c) a/Toff
	d) α/Ton
9	Find the output voltage expression for a step down chopper with Vs as the input
	voltage and α as the duty cycle.
	a) $Vo = Vs/\alpha$
	b) $\mathbf{Vo} = \mathbf{Vs} \mathbf{x} \boldsymbol{\alpha}$

	c) Vo = Vs ² / α
	d) Vo = $2Vs/\alpha\pi$
10	The below given figure is that of a (IGBT is used as a chopper switch)
	a) step-up/step-down chopper
	b) step-down chopper
	c) step-up chopper
	d) none of the mentioned
11	If a step up chopper's switch is always kept off then (ideally)
11	a) $V_0 = 0$
	$\begin{array}{c} a \\ b \\ b \\ \end{array} Vo = \infty$
	c) $\mathbf{V}0 = \mathbf{V}\mathbf{S}$
	d) $V_0 > V_S$
12	If a step up chopper's switch is always kept open then (ideally)
12	a) $V_0 = 0$
	b) $\mathbf{V}_{0} = \infty$
	c) $V_0 = V_S$
	d) $V_0 > V_S$
13	Find the average value of output voltage of a basic step-down chopper, with duty
	cycle = α and load = R Ω .
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	····[································
	│ · · · └────────── ─ ───── ─ ──── ─ ──── ─ ──────
	a) $I = Vs x \alpha$
	b) $\mathbf{I} = (\mathbf{Vs} \mathbf{x} \alpha)/\mathbf{R}$
	c) $\mathbf{I} = 0$
	d) $I = Vs/R$
14	For a step-up chopper, when the duty cycle is increased the average value of the
	output voltage
	a) increases
	b) decreases
	c) remains the same
	d) none of the mentioned

15	For a step-down chopper, when the duty cycle is increased the average value of
	the output voltage
	a) increases
	b) decreases
	c) remains the same
	d) none of the mentioned
16	The below given chopper circuit is that of a
10	
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	a) step-up chopper
	b) step-down chopper
	c) step-up/step-down chopper
17	d) none of the mentioned
1/	The expression for a step-up/step-down chopper with α as the duty cycle and Vs
	as the dc input voltage is
	a) $VS/1 - \alpha$
	b) $\alpha \times Vs$
	c) VS $(\alpha/1-\alpha)$
10	d) VS $(\alpha/1+\alpha)$ Even a star un (star down channen if α (dute could) = 0.5 then
18	For a step-up/step-down chopper, if α (duty cycle) = 0.5 then
	a) $\mathbf{V}0 = \mathbf{V}\mathbf{S}$
	b) $VO < VS$
	c) $v_0 > v_s$
10	d) none of the mentioned
19	In the figure shown below, the capacitor C is used to
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	la la se ₩₩esse la secchiera e la secola la secola de la s
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	Γ.Δ
	a) maintain the load maltage constant
	a) manuali the load
	b) protect the load
	c) protect the chopper switch (Sw)
20	a) maintain the load current constant Ease state exp(stare degree if α (but $\alpha = 1$) < 0.5.1
20	For a step-up/step-down chopper, if α (duty cycle) < 0.5 then
	a) $\mathbf{v}\mathbf{o} = \mathbf{v}\mathbf{s}$

	b) Vo < Vs
	c) $Vo > Vs$
	d) none of the mentioned
21	In the below shown step-up/step-down chopper circuit, when the chopper switch
	(SW) if first on and then off, then the current flows from path
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	li l
	(+)vs · · · · · · · · · · · · · · · · · · ·
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	a) Vs-CH-L-Vs
	b) L-Load-D-L
	c) L-D-Load-L
	d) no current flows
22	A step-down chopper is also called as a
	a) first-quadrant chopper
	b) second-quadrant chopper
	c) third-quadrant chopper
	d) fourth-quadrant chopper
23	For the type-B chopper shown below
	t (+)vs to
	· · · · · · · · · · · · · · · · · · ·
	a) during T_{on} , $Vo = 0$ and L stores energy
	b) during T_{on} , Vo is not 0 and L stores energy
	c) during T_{on} , $Vo = 0$ and L releases energy
	d) during T _{on} , Vo is not 0 and L releases energy
24	The below given chopper is that of a
	¹⁷
	1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 3 1.
	· (+)vs · · · · · · · · · · · · · · · · · · ·
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	a) step-up chopper
	b) step-down chopper





	a) CH1, FD
	b) CH2, FD
	c) CH1, D2
	d) CH2, D2
32	Which type of chopper is used in the regenerative braking of DC motors?
	a) type A
	b) type B
	c) type C
	d) type D
33	Type C chopper consists of
	a) two diodes and two switches
	b) one diode and one switch
	c) one diode and three switches
	d) three diodes and two switches
34	In a type C chopper, if only one switch is operated
	a) only one quadrant operation will be obtained
	b) two quadrant operation can be obtained
	c) the chopper won't work
	d) none of the mentioned
35	A type D chopper is a
	a) two quadrant type-B chopper
	b) two quadrant type-A chopper
	c) two quadrant type-C chopper
	d) none of the mentioned
36	In a type-D chopper
	a) current can flow in both the directions of the load
	b) current cannot flow in both the directions of the load
	c) voltage can only be positive
	d) voltage can only be negative
37	For a type D chopper, the average value of output voltage will be positive when
	a) $T_{on} = T_{off}$
	b) $T_{on} < T_{off}$
	c) $T_{off} = 0$
	d) $T_{on} > T_{off}$
38	For a type D chopper, if duty cycle $= 0.5$ then the
	a) average voltage is positive
	b) average voltage is negative
	c) average voltage is zero
	d) chopper cannot be operated with duty cycle = 0.5



	c) Ist, IInd and IIIrd quadrants
	d) all the four quadrants
44	For the first quadrant operation of type E chopper
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	a) Only CH1 is on
	b) CH1 and CH2 is on
	c) CH1 and CH3 is on
	d) CH1 and CH4 is on
45	What is the expression for load voltage when the chopper is operated in the
10	second quadrant?
	a) Vs
	b) E
	c) 0
	d) $\mathbf{E} + \mathbf{L} \mathbf{d} \mathbf{i} / \mathbf{d} \mathbf{t}$
46	The load emf E must be reversed for
10	a) first and second quadrant operation
	b) third quadrant operation
	c) fourth quadrant operation
	d) both third and fourth quadrant operation
47	For the type E chopper to be operated in the fourth quadrant
	a) only one switch is operated
	b) two switches are operated
	c) three switches are operated
	d) all the switches are operated
48	In a type E chopper, if all the four chopper switches are closed simultaneously
	then
	a) load is short circuited
	b) supply is short circuited
	c) both load and supply are shorted
	d) none of the mentioned.



	Unit 4: INVERTERS AND UPS
1	Inverters converts
	a) dc power to dc power
	b) dc power to ac power
	c) ac power to ac power
	d) ac power to dc power
2	Line-commutated inverters have
	a) AC on the supply side and DC on the load side
	b) AC on both supply and load side

	c) DC on both supply and load side d DC on the supply side and AC on the load side
3	In a VSL (Voltage source inverter)
5	$a^{(1)}$ the internal impodance of the DC source is negligible
	b) the internal impedance of the DC source is very very high
	c) the internal impedance of the ΔC source is negligible
	d) the IGBTs are fired at 0 degrees
4	d) the IOD I's are filled at 0 degrees.
4	a) IGRT
	$\mathbf{b} \mathbf{CTO}$
	c) PMOSEET
	d) SCB
5	Identify the circuit given below
5	
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	$[\cdot, (\underline{\tau})^{N^2}, \ldots, \ldots, \underline{\gamma}^{T^2}, \ldots, \underline{\gamma}^{T^2}$
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	a) Half wave series inverter
	b) Full wave series inverter
	c) Half wave bridge inverter
	d) Half wave parallel inverter
6	Single phase half bridge inverters requires
	a) two wire ac supply
	b) two wire dc supply
	c) three wire ac supply
7	d) three wire dc supply
/	what is the voltage across the R load when only 11 is conducting?
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	$[\cdot, \cdot]^{\mathcal{N}}$ base of \mathcal{A} .
	$[\cdot, (\underline{+})^{M_2}, \ldots, \ldots, \ldots, \underline{+}^{T_2}, \ldots, \underline{+}^{T$
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	a) Vs
	b) Vs/2
	c) 2Vs
8	In a single-phase half wave inverter SCR(s) are/is gated at a time.
	a) one
	D) TWO
	c) three d) none of the mentioned
1	a) none of the mentioned

9	What is the voltage across the R load when only T2 is conducting?
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	· (+)w₂ · · · · · · · · · · · · · · · ·
	a) Vs
	b) $Vs/2$
	c) $2Vs$
	d) Zero
10	The voltage in a single phase half wave inverter varies between
-	a) Vs and 0
	b) $Vs/2$ and 0
	c) $Vs/2$ and $-Vs/2$
	d) Vs and –Vs
11	The output of a single-phase half bridge inverter on R load is ideally
	a) a sine wave
	b) a square wave
	c) a triangular wave
	d) constant dc
12	The output current wave of a single-phase full bridge inverter on RL load is
	a) a sine wave
	b) a square wave
	c) a triangular wave
	d) constant dc
13	Single-phase full bridge inverters requires
	a) 4 SCRs and 2 diodes
	b) 4 SCRs and 4 diodes
	c) 2 SCRs and 4 diodes
1.1	d) 2 SCRs and 2 diodes
14	Identify the circuit given below.
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	Υ ^{T1} Δ ^{D1}
	$(+)_{\pm Ns}$
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	$\begin{array}{c} \begin{array}{c} \begin{array}{c} \\ \end{array} \end{array}$
	a) Full wave series inverter b) Helf wave series inverter
	c) Full wave bridge inverter
	d) Full wave parallel inverter
1	u) run wave paraner inverter

15	The output voltage from a single phase full wave bridge inverter varies from
	a) Vs to –Vs
	b) Vs to zero
	c) $Vs/2$ to zero
	d) $-Vs/2$ to $Vs/2$
16	In a single phase full wave bridge inverter, when the output is Vs or $-Vs$
	a) one SCR and one diode are conducting
	b) four SCRs are conducting
	c) two SCRs are conducting
	d) two diodes are conducting
17	In the following circuit, the diodes D1 to D4 are used to
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	a) reduce the switching losses
	b) send current back to the dc source when SCRs are off
	c) send current back to the load when SCRs are off
10	d) send current back to the dc source when SCRs are conducting
18	For a full wave bridge inverter, the output voltage (Vo)
	a) $Vo = Vs/2$ for $0 < t < 1/2$
	b) $V_0 = V_S \text{ for } 0 < t < 1/2$
	c) Vo = Vs for $1/2 < t < 1$
10	d) $V_0 = -V_s$ for $1/2 < t < 31/2$
19	For a half wave bridge inverter, the output voltage
	a) $VO = -VS/2$ for $U < t < 1/2$
	b) $V_0 = -V_{s/2} \text{ for } 1/2 < t < 1$
	c) $VO = -VS$ for $U < t < 1/2$
20	d) $VO = VS/2$ for $1/2 < t < 1$
20	In a half wave circuit, forced commutation is essential when the
	a) load is inductive
	b) load is resistive
	c) source voltage is below 150 v
21	d) none of the mentioned
21	In VSI (voltage source inverters)
	a) both voltage and current depend on the load impedance
	b) only voltage depends on the load impedance
	c) only current depends on the load impedance
22	a) none of the mentioned
22	In the single-pulse width modulation method, the output voltage waveform is
	symmetrical about
	a) π

	b) 2π
	c) $\pi/2$
	d) π/4
23	In the single-pulse width modulation method, the output voltage waveform is
	symmetrical about in the negative half cycle.
	a) 2π
	b) 3 π/2
	c) π/2
	d) 3π/4
24	The shape of the output voltage waveform in a single PWM is
	a) square wave
	b) triangular wave
	c) quasi-square wave
	d) sine wave
25	A three-phase bridge inverter requires minimum of switching
	devices.
	a) 3
	b) 4
	c) 6
	d) 8
26	In the three-phase bridge inverter, each step consists of
	a) 30°
	b) 60 °
	c) 90°
	d) will depend on the value of the firing angle
27	In inverters, to make the supply voltage constant
	a) an inductor is placed in series with the load
	b) capacitor is connected in parallel to the load side
	c) capacitor is connected in parallel to the supply side
20	d) none of the mentioned
28	In the 180° mode VSI, devices conduct at a time.
	(b) 2
20	(1) 4 In voltage fed themister inverters
29	a) load
	b) forced
	c) self
	d) any commutation technique can be used
30	What is the maximum line voltage value in case of a three-phase VSI in 180°
50	mode?
	a) 2Vs
	b) Vs
	c) 3Vs
	d) 2Vs/3
31	The 120° mode of operation of a three phase bridge inverter requires
	number of steps.
	a) 2
	b) 4

	c) 6
	d) 8
32	In case of the 120° mode of operation, devices conduct at a time.
	a) 2
	b) 3
	c) 4
	d) none of the mentioned
33	Safe commutation can be achieved in case of the operating mode.
	a) 180°
	b) 120 °
	c) 360°
	d) none of the mentioned
34	Several equidistant pulses per half cycle are used in type of
	modulation technique.
	a) single-pulse
	b) multiple-pulse
	c) sine-pulse
	d) equidistant-pulse
35	In the MPM method, the comparator is given and types of
	waveform at its input.
	a) square, sine
	b) square, quasi-square
	c) sine, triangular
	d) square, triangular
36	In MPM, the square wave is the signal whereas the triangular wave is
	the signal.
	a) reference, carrier
	b) base, reference
	c) carrier, reference
	d) none of the mentioned
37	In the multiple pulse width modulation method, the firing pulses are generate
	during the interval when the
	a) triangular wave exceeds the square modulating wave
	b) square modulating wave exceeds the triangular wave
	c) square wave amplitude is same as the triangular wave's amplitude
20	d) none of the mentioned
38	In type of modulation method, the pulse width is not equal for all
	the pulses.
	a) multiple pulse width modulation
	b) single pulse width modulation
	c) sinusoidal pulse width modulation
20	d) none of the mentioned
39	In sinusoidal pulse width modulation, wave is compared with a
	type of wave.
	a) square, sinusoidal
	D) sinusoidai, trianguiar
	c) sinusoidai, quasi-square
40	a) none of the mentioned
40	In the sinusoidal pulse width modulation, is the carrier wave signal.
	a) square wave

	b) triangular wave
	c) sinusoidal wave
	d) quasi-square wave
41	In the sinusoidal pulse width modulation, is the reference wave
	signal.
	a) square wave
	b) triangular wave
	c) sinusoidal wave
	d) quasi-square wave
42	In sinusoidal pulse width modulation, the comparator output is high when the
	a) triangular wave has magnitude higher than the sinusoidal wave
	b) sinusoidal wave has magnitude higher than the triangular wave
	c) triangular wave has magnitude equal to the sinusoidal wave
	d) none of the mentioned
43	In PWM, the comparator output is further given to a
_	a) integrator
	b) scr devices
	c) trigger pulse generator
	d) snubber circuit
44	The modulation index (MI) is given by
	Vr = peak value of the reference wave.
	Vc = peak value of the carrier wave.
	a) Vr/Vc
	b) Vc/Vr
	c) $(1 + Vc/Vr)$
	d) $1/(Vc Vr)$
45	By controlling the modulation index (MI). can be controlled.
-	a) gain
	b) output frequency
	c) harmonic content of the output voltage
	d) cosine component of the output voltage
46	In pulse width modulated inverters, the output voltage is controlled by controlling
-	the
	a) input frequency
	b) modulating index
	c) amplification factor
	d) none of the mentioned
47	Increasing the number of pulses (N).
-	a) reduces the output voltage amplitude
	b) reduces the inverter efficiency
	c) improves the inverter efficiency
	d) none of the mentioned
48	A VSI will have a better performance if its
	a) load inductance is small and source inductance is large
	b) both load inductance and source inductance are small
	c) both load inductance and source inductance are large
	d) none of the mentioned
49	Control of frequency and control of voltage in 3-phase inverters is
	a) possible only through inverter control circuit
	b) possible through the control circuit of inverter and converter
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	c) possible through inverter control of frequency and through converter
	control for voltage
	d) none of the mentioned
50	Output voltage of a single-phase bridge inverter, fed from a fixed dc source is
	varied by
	a) varying the switching frequency
	b) pulse-width modulation
	c) pulse amplitude modulation
	d) all of the mentioned

	Unit 5. CYCLOCONVERTERS
1	A cycloconverter is a
	a) one stage power converter
	b) one stage voltage converter
	c) one stage frequency converter
	d) none of the mentioned
2	Applications of cycloconverters include
	a) speed control of ac drives
	b) induction heating
	c) static VAr compensation
	d) all of the mentioned
3	The single phase mid-point type cycloconverter uses number of
	SCRs.
	a) 4
	b) 8
	c) 6
	d) none of the mentioned
4	The single phase bridge type cycloconverter uses number of SCRs.
	a) 4
	b) 8
	c) 6
	d) none of the mentioned
5	In the positive half cycle from $\omega t = 0$ to π
	· · · · · · · · · · · · · · · · · · ·
	Load
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	a) P1 and P2 are forward biased
	b) N1 and P2 are forward biased



	c) (input frequency/output frequency) ^{-1/2}
	d) (input frequency/output frequency) $^{1/2}$
10	In a three phase half-wave cycloconverter
	a) both inverting and converting action takes place
	b) only inversion action takes place
	c) only converting action takes place
	d) none of the mentioned
11	A cycloconverter is a
	(a) Frequency changer from higher to lower frequency with one-state conversion
	(b) Frequency changer from higher to lower frequency with two-stage conversion
	(c) Frequency changer from lower to higher frequency with one-stage conversion
	(d) Either a or c
12	The cycloconverter require natural or forced commutation as under
	(a) Natural commutationin bothstep-up and step down cycloconverter
	(b) Forced commutation in both step-up and step-down cycloconverter
	(c) Forced commutation in step-up cycloconverter
	(d) Forced commutation in step-down cycloconverter
13	The quality of output ac voltage of a cycloconverter is improved with
	a)Increase in output voltage at reduced frequency
	b)Increase in output voltage at increased frequency
	c) decrease in output voltage at reduced frequency
	d) decrease in output voltage at increased frequency
14	four quadrant chopper cannot be operated as
	a)One quadrant chopper
	b)Cycloconverter
	c) Inverter
	d)Bidirectional rectifier
15	A cycloconverter converts:
	a)AC to DC
	b)DC to AC
	c)DC to DC with different level
	d)AC to AC at different frequencies
16	AC voltage controllers convert
	a) fixed ac to fixed dc
	b) variable ac to variable dc
	c) fixed ac to variable ac
	d) variable ac to fixed ac
17	In AC voltage controllers the
	a) variable ac with fixed frequency is obtained
	b) variable ac with variable frequency is obtained
	c) variable dc with fixed frequency is obtained
	d) variable dc with variable frequency is obtained
18	Earlier then the semiconductor technology, devices were used for
	voltage control applications.
	a) cycloconverters
	b) vacuum tubes
	c) tap changing transformer
	d) induction machine

19	The AC voltage controllers are used in applications.
	a) power generation
	b) electric heating
	c) conveyor belt motion
	d) power transmission
20	In the principle of phase control
	a) the load is on for some cycles and off for some cycles
	b) control is achieved by adjusting the firing angle of the devices
	c) control is achieved by adjusting the number of on off cycles
	d) control cannot be achieved
21	A single-phase half wave voltage controller consists of
	a) one SCR is parallel with one diode
	b) one SCR is anti parallel with one diode
	c) two SCRs in parallel
	d) two SCRs in anti parallel
22	Pulse gating is suitable for
	a) R loads only
	b) R and RL loads
	c) RL loads only
	d) all types of loads
23	In continues gating
	a) overlap angle is very high
	b) SCR is heated up
	c) size of the pulse transformer is small
	d) commutation cannot be achieved effectively
24	High frequency gating uses a
	a) train of pulses
	b) continuous gating block
	c) carrier signal
	d) none of the above
25	A single-phase sinusoidal voltage controller has
	a) one primary and n secondary windings
	b) one primary and (n-1) secondary windings
	c) n primary and n secondary windings
	d) (n-1) primary and n secondary windings
26	Sequence control of ac voltage controllers is employed for the improvement of
	a) output frequency
	b) input frequency
	c) commutation
	d) system power factor
27	A two stage sequence control is
	a) two SCRs in anti parallel
	b) two voltage controllers in parallel
	c) two voltage controllers in series
	d) a voltage controller having two voltage level
28	From the below given statements regarding sequence control of ac voltage, which
	of them are true?
	i) It improves system power factor
	ii) It reduces the harmonic content at the output





c) speed control of universal motor
d) none of the mentioned